

## Announcement for Autonomy Technology Team Project

### Getting Started: Roboracer

#### Motivation

Autonomous racing represents one of the most challenging and exciting applications of autonomous driving technology. Unlike conventional self-driving vehicles, race cars operate at the limits of handling, requiring ultra-fast decision-making, precise trajectory planning and tracking, and real-time adaptation to dynamic conditions. The Roboracer project aims to establish a research platform for testing and developing cutting-edge AI-driven planning and control strategies in a high-performance setting.

Through this project, students will gain hands-on experience in developing autonomous systems that can handle high-speed scenarios, optimize decision-making under uncertainty, and push the boundaries of state-of-the-art algorithms. Furthermore, the technologies developed for racing environments can contribute to advancements in real-world autonomous driving applications, making this an ideal project for those passionate about robotics, AI, and autonomy.

#### Task description

This project will focus on the initial setup and foundational work required to participate in future Roboracer challenges

- Setup the code base
- Get started within the Roboracer simulation
- Identify necessary steps to successfully participate in future challenges
- Implement and compare existing perception and planning frameworks
- (Hardware setup and real world tests)

The specific task assignment can be further defined based on the existing knowledge.

#### Requirements

- Strong motivation and commitment, along with the ability to work independently
- Advanced studies in Autonomy Technologies
- Knowledge in at least one of the following areas: modeling, control, optimization, AI
- Solid programming skills, preferably in Python, C++, as well as ROS2

If you have any questions, please feel free to contact Philipp Hartmann (see below).

#### Contact

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